EE424 Homework 9

1) Suppose that the system function of an LTI system is

$$H(z) = \frac{1+z^{-1}}{\left(1-\frac{1}{2}z^{-1}\right)\left(1-2z^{-1}\right)\left(1-3z^{-1}\right)}$$

- (a) Determine the ROC of H(z) if it is known that the system is stable.
- (b) Determine the ROC of H(z) if it is known that the system is causal.
- (c) Is it possible for the system to be both stable and causal?
- 2) The input to a causal LTI system is

$$x[n] = \left(\frac{1}{4}\right)^n u[n]$$

The z-transform of the output of this system is

$$Y(z) = \frac{1}{\left(1 - \frac{1}{4}z^{-1}\right)\left(1 - \frac{1}{2}z^{-1}\right)}$$

- (a) Determine the system function H(z), specify the ROC of H(z).
- (b) What is the ROC for Y(z)?
- (c) Determine the output sequence y[n].
- 3) The system function of a causal LTI system is

$$H(z) = \frac{1 - \frac{1}{4} z^{-1}}{\left(1 - \frac{1}{3} z^{-1}\right)\left(1 - \frac{1}{2} z^{-1}\right)}$$

The input to the system is

$$x[n] = \left(\frac{1}{4}\right)^n u[n]$$

Find the output sequence y[n].